EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	63	318/560-632.ccls. and synchronous and motor and position and (speed or velocity) and servo adj motors and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L2	4	318/66-85.ccls. and synchronous and motor and position and (speed or velocity) and servo adj motors and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L3	19	318/66-85.ccls. and synchronous and motor and position and (speed or velocity) and servo and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L4	19	318/66-85.ccls. and synchronous and motor and position and (speed or velocity) and servo and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L5	0	318/98.ccls. and synchronous and motor and position and (speed or velocity) and servo and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L6	3	318/98.ccls. and synchronous and motor and position and (speed or velocity) and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:56
L7	1	318/99.ccls. and synchronous and motor and position and (speed or velocity) and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:57
L8	16	318/52.ccls. and synchronous and motor and position and (speed or velocity) and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:57

L9	82	318/700.ccls. and synchronous and motor and position and (speed or velocity) and feedback	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:57
L10	6	(synchronous and servo adj motor and position and (speed or velocity) and feedback).CLM.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:57
L11	17	(synchronous and servo and motor and position and (speed or velocity) and feedback).CLM.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/10/26 08:57